

USER GUIDE



SET PRO BY SOMFY SDN CONFIGURATION TOOL

FEATURES & USER GUIDE
VERSION 1.1



Contents

1.	About Software	4
1.1.	Software Version	4
1.2.	Device Compatibility	4
1.3.	Recommendations	4
2.	Project Management	5
2.1.	Create New Project.....	5
2.2.	Import Project.....	6
2.3.	Search Project.....	6
2.4.	Delete Project	6
2.5.	Export Project	7
3.	Project Space Overview	8
3.1.	Project Header	9
3.2.	Serial Port Option	9
4.	Floor Plan Operations	10
4.1.	Add Floor	10
4.2.	Add Room	11
4.3.	Search Floors/Rooms/SDN Devices.....	11
4.4.	Project View.....	11
4.5.	Options and operations available for Floors/Rooms/SDN Devices in Floor Plan.....	12
4.5.1.	Floor Options	12
4.5.2.	Room Options.....	12
4.5.3.	SDN Device options	12
5.	Device Map	14
5.1.	Discover SDN Devices	14
5.1.1.	Discover SDN Motors	14
5.1.2.	Discover Keypad.....	15
5.2.	Identify Motor	15
5.3.	Search SDN Devices.....	16
5.4.	Clear Unassigned Discovered Devices	16
5.4.1.	Clear Individual Device.....	16
5.4.2.	Clear All Unassigned Devices	16
5.5.	Assign Devices in Room	16
5.6.	Create Group Map	18
5.7.	Create New Group	18

5.8.	Assign Motors to Group.....	18
5.9.	Group Operations	19
6.	Device Config.....	20
6.1.	Open Device Config Tab.....	20
6.2.	Motor Config Options	20
6.2.1.	Control Tab.....	20
6.2.2.	Intermediate Positions (IPs).....	21
6.2.3.	Motor Group.....	22
6.2.4.	Motor Settings.....	23
	6.2.4.1 Motor End Limit adjustment.....	23
	6.2.4.2 Direction adjustment.....	23
	6.2.4.3 Speed adjustment.....	23
	6.2.4.4 Lock Set up.....	23
6.2.5.	Action	25
6.2.6.	Diag.....	25
6.3.	Keypad Configuration	25
6.4.	RTS Receiver Configuration	26
	6.4.1 Group Operations	26
7.	Communication Log.....	27
7.1	Open Communication Log.....	27
7.2	Communication Log features.....	27

1. About Software

1.1. Software Version

Set pro by Somfy Version 2.0.8

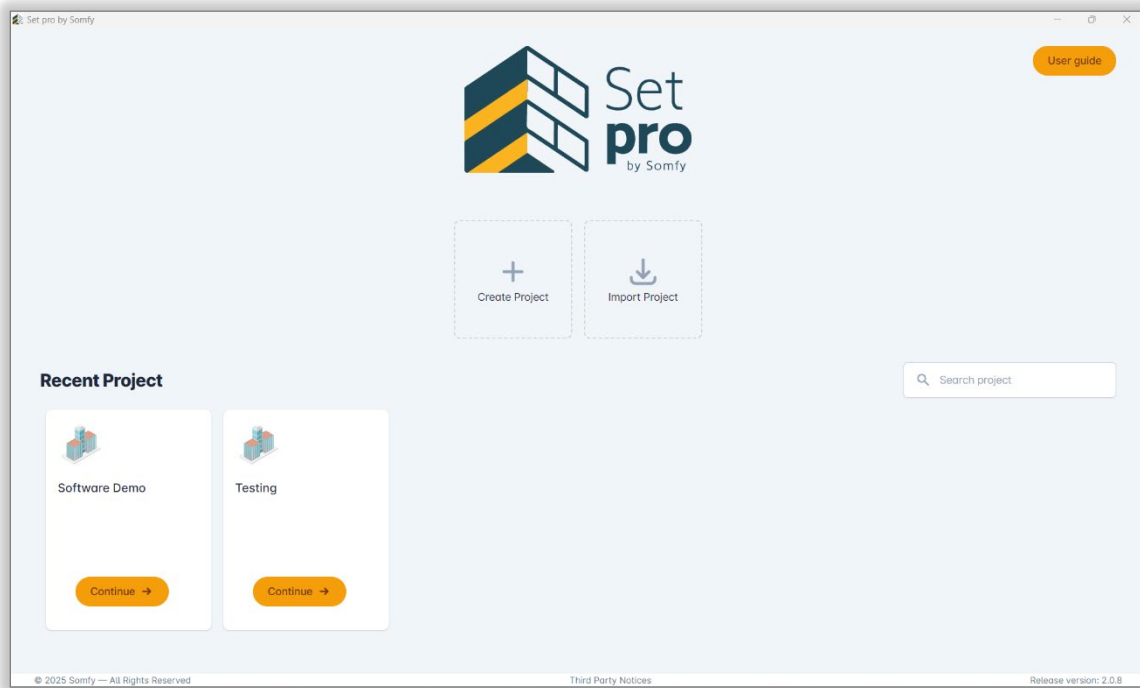
1.2. Device Compatibility

Device	Support	Compatibility
Sonnesse® 30 RS485 (1241144)	Yes	
Sonnesse® 30 RS485 (1000658)	Yes	
Sonnesse® 40 AC RS485	Yes	
Sonnesse® ULTRA 50 DC RS485	Yes	
Sonnesse® ULTRA 50 AC RS485	Yes	
Sonnesse® 50 AC RS485	Yes	
LT50 AC RS485	Yes	
RS485 Motor Limit Setting Tool (Rev. A/B)	Yes	
RS485 Motor Limit Setting Tool (Rev. C)	Yes	
Glydea® ULTRA 35 & 60	Yes	
Rs485 (SDN) Module For Irismo™ Motors	No	
Decoflex SDN Keypad V2	Yes	Firmware Version >= 5.54
RTS Receiver For SDN V2	Yes	Firmware Version >= 2.00
ILT2 Motors	Yes	
RTS Transmitter (Situo/Telis)	No	

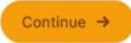
1.3. Recommendations

- Somfy SDN Data Hub V2 does not support data rates used in motor firmware update. It's recommended to not use the SDN Data Hub V2 while updating motor firmware. Use an RJ45 Coupler or other passive hub to update motor firmware.
- Firmware update for following motors/devices is not supported by this software.
 - Sonnesse® 30 RS485
 - Glydea® ULTRA 35 & 60
 - Decoflex SDN Keypad V2
 - RTS Receiver For SDN V2
- The RS485 Limit Setting Tool is not discoverable with this software. The only operation allowed for Limit Setting Tool is firmware updating.

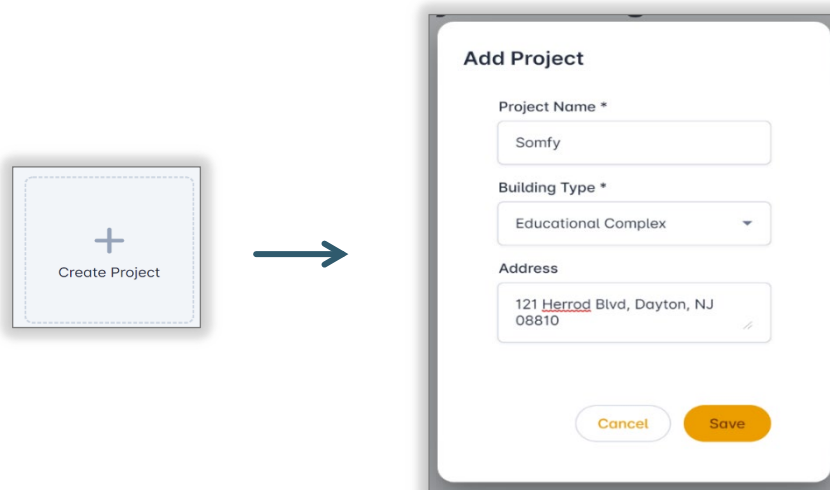
2. Project Management



NOTE: [Refer to Appendix A of this guide](#) to import projects from previous software versions.

Project space allows to Create, Search, Open, Delete, and Import SDN projects. A list of all the projects in the local machine will be displayed here. Click on the  button to select a project.

2.1. Create New Project



Click on "Create Project" to create new Project. Fill in the window fields with required project details.

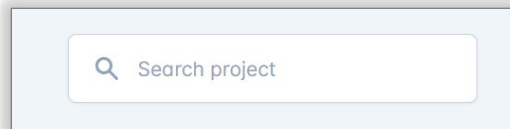
Click on "Save" to create project.

2.2. Import Project



Click on "Import Project" to open a window to select SDN Set pro Configuration Tool project.
Add file by either drag and drop or click "Browse for file" on the local machine.

2.3. Search Project



Click in "Search project" field and type to search by project name.
NOTE: Only projects with matching names will be displayed.

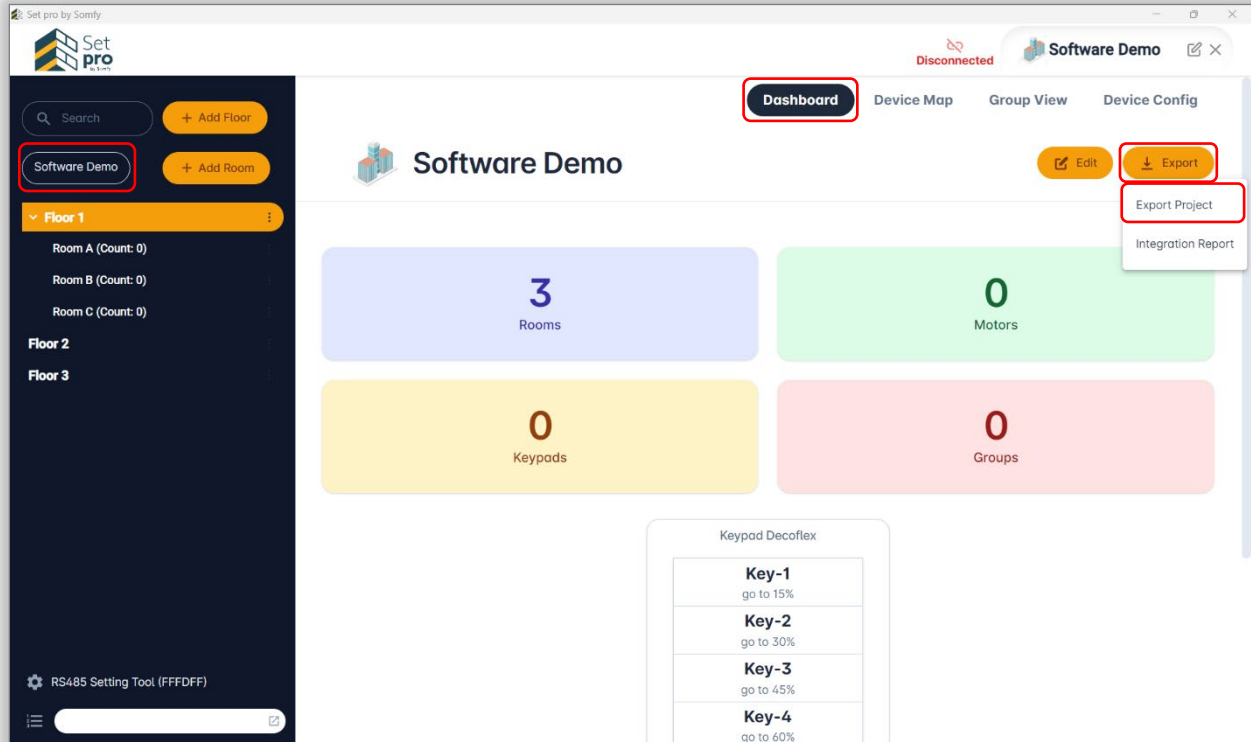
2.4. Delete Project



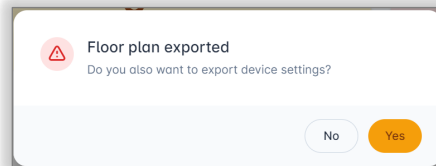
Delete project option is available when hovering over the project tile.
NOTE: Tooltip for delete icon is displayed when cursor is over that icon.
Once a project is deleted, a prompt opens to confirm the action. Once confirmed, the project is cleared from the project space and related files are deleted from the local machine.

***** IMPORTANT*** Delete project cannot be undone!**

2.5. Export Project



Open the project, Select the Dashboard Tab, Click the “Export” Button, Select “Export Project”.



If only floor plan is to be exported, click “No” on the popup window, otherwise click “Yes”.

When exporting/importing a project with device settings,

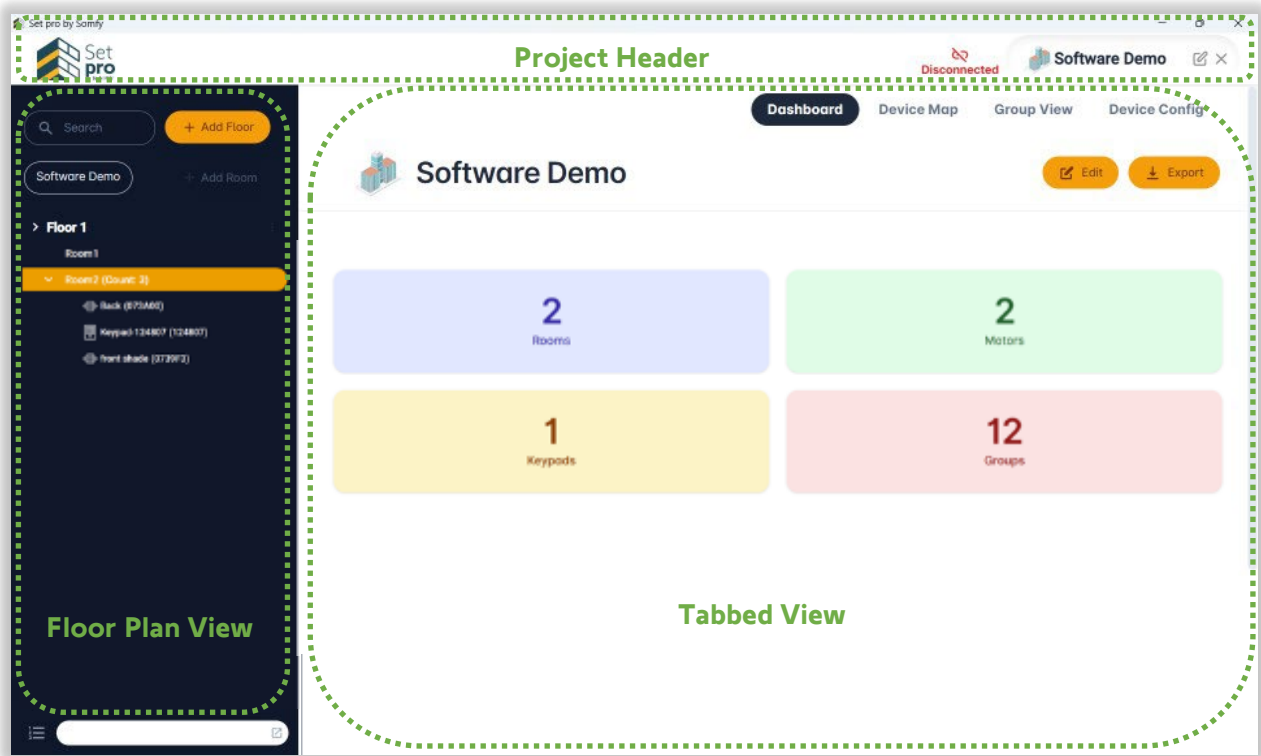
Exporting: The latest device settings will be read from all devices assigned into the floor plan.

Importing: All imported device settings are written on the SDN devices.

The following parameters are exported for the project:

- Motor: Intermediate Position, Group, and Network Settings
- Keypad: Keypad Settings
- RTS Receiver: Group Settings

3. Project Space Overview



The Project Header displays on the top of the Project Space. Project Header provides the serial connection option, Project details and options to close/export project or edit project details.

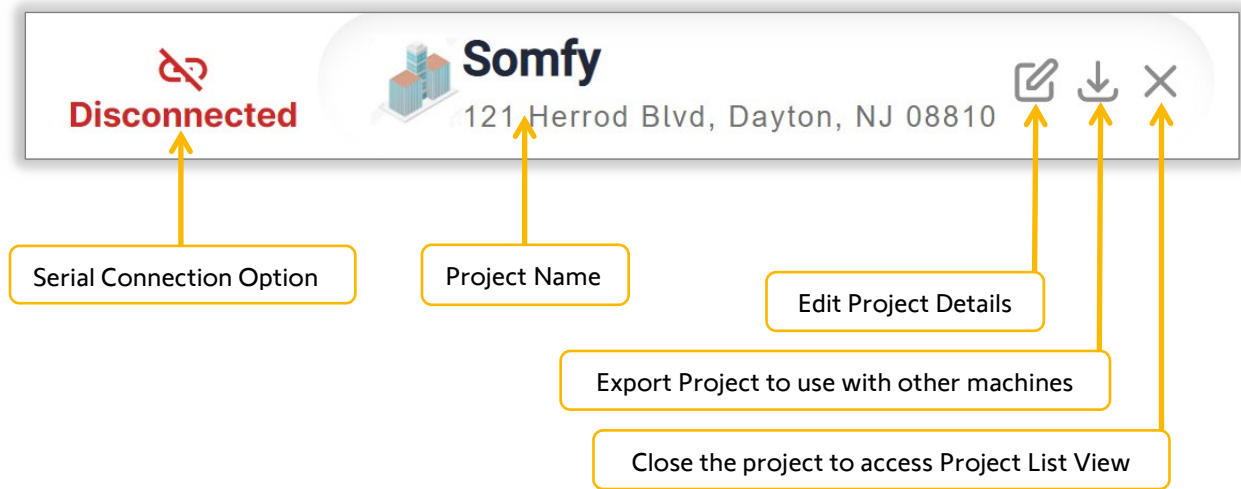
Floor Plan View is on left side of the window. Floor Plan View displays a tree view containing floors, rooms and SDN devices assigned to floors/rooms. Progress bar and shortcut to open communication log is displayed in bottom part of the floor plan.

- Progress Bar: Displays status of current SDN message queue in progress.
- Communication Log: Clicking this option will open log of SDN communication for ongoing session.

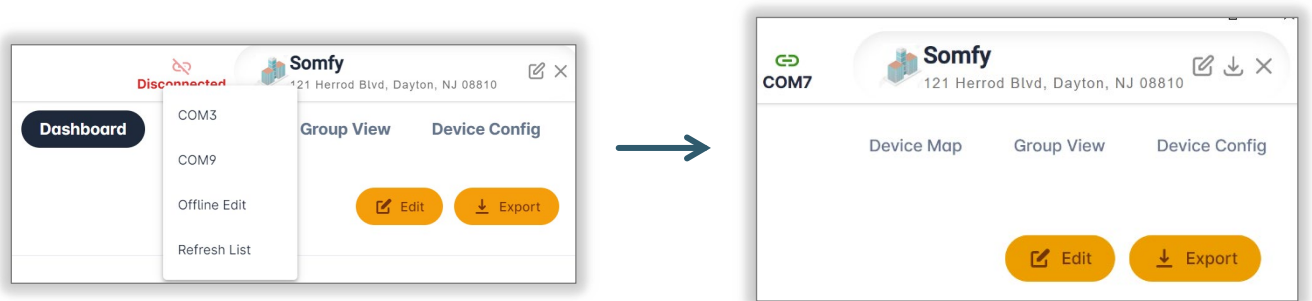
The Tabbed View is on right side of the window. Tabbed View contains tabs for Device Map, Group View, and Device Config.

- Device Map: Provides option to discover SDN Devices (i.e. SDN Motors and SDN Keypads), displays list of discovered devices and list of assigned/unassigned SDN Devices to floor plan.
- Group View: Provides option to create/manage/delete groups. List all groups of SDN motors in project, each device in group. User is able to create/delete group here and assign motors to groups.
- Device Config: Provides user interface to manage individual SDN devices. Configuration options for selected SDN device in Floor Plan appears in this interface.

3.1. Project Header

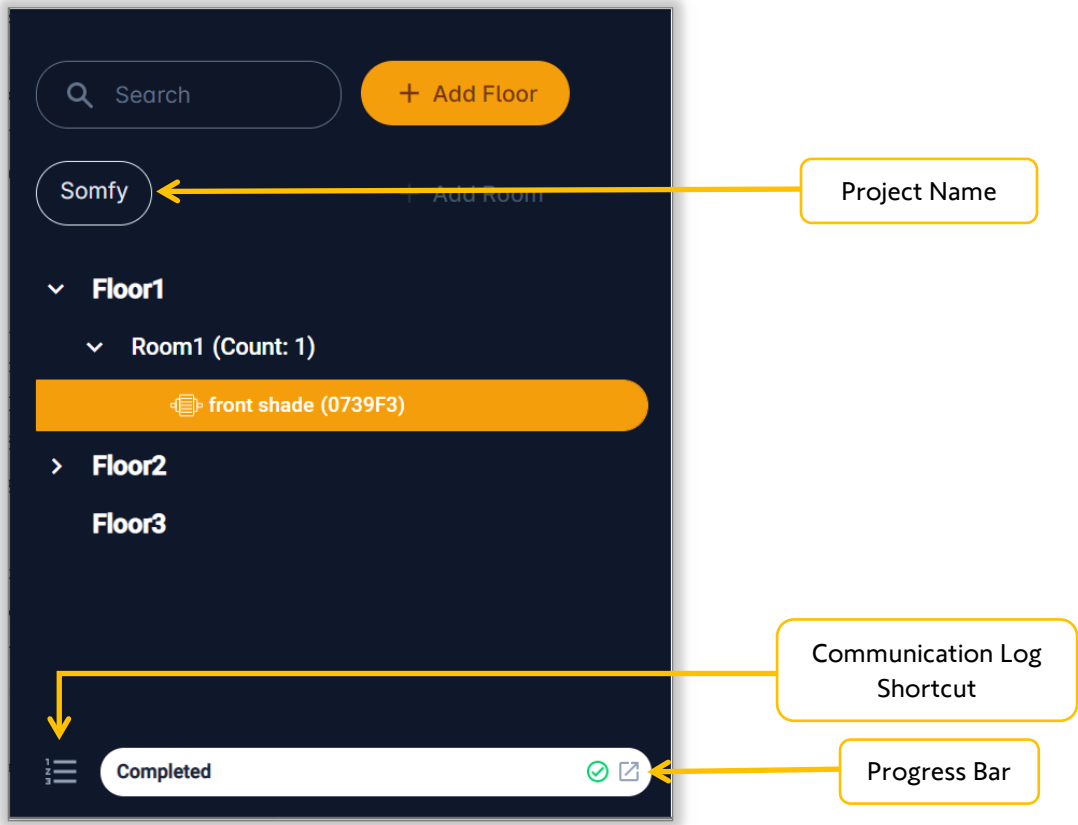


3.2. Serial Port Option

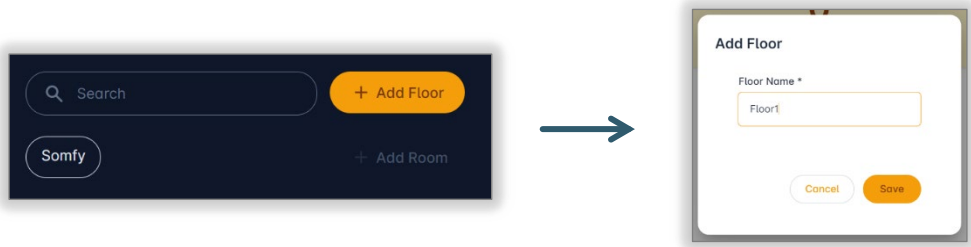


- Serial Connection Option keeps flashing until Serial Connection is made **Disconnected**
- Clicking on the Serial Connection Option opens a list of ports available for serial connection
- Once serial connection is established, the port name is displayed
- To disconnect from port, click the Serial Connection Option and it will disconnect the serial port
- For offline programming, select "Offline Edit"

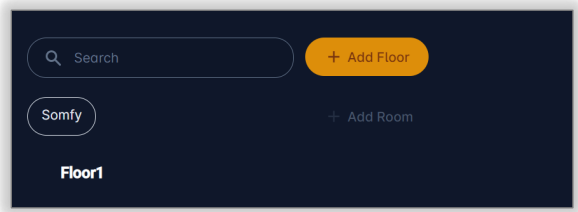
4. Floor Plan Operations



4.1. Add Floor





Click on the **+ Add Floor** button to add new floor. A prompt will ask the user to enter floor name.
Click on **Save** and floor will appear in floor plan view.



NOTE: Two floors with same name cannot be created. A floor cannot be created without name.

4.2. Add Room

Click the desired floor to create room. Floor name and  button will be highlighted. Click on  to add a new room. User is prompted to enter room name and it will appear for the room.

NOTE: Rooms can't have the same name in the same floor, different floors allow the same room name.

4.3. Search Floors/Rooms/SDN Devices

Use the Search Bar to search Floor, Room or SDN device with name.

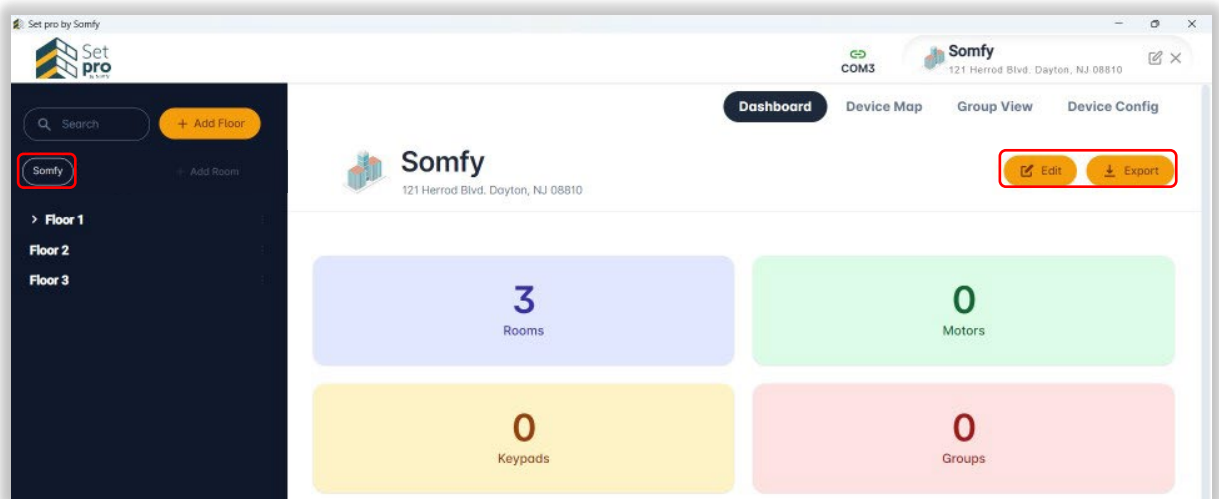
Floor: Floors can be searched by Floor Name. Only Floors containing searched term in Floor Name will be displayed. All rooms and SDN devices within that floor will also be displayed

Rooms: Rooms can be searched by Room Name. Only rooms containing searched term will be displayed along with related Floor and all SDN devices within that room.

SDN Devices: SDN devices can be searched with Device Name/ Device ID. Only devices containing searched terms will be displayed along with related Room and Floor.

4.4. Project View

Click on the Project Name in Floor Plan View to open Project Dashboard in Tabbed View



Top right corner of Dashboard has two buttons

1. Edit: To edit project details (Project Name, Building Type, Address)
2. Export: Export project has following options
 - a. Export Project: Exports a project file to be saved or used on other devices
 - b. Integration Report: Generates and excel file containing Device Information with floor details and Group Information

4.5. Options and operations available for Floors/Rooms/SDN Devices in Floor Plan



Floor/Room/SDN Device options are available via the 3-dot menu when cursor is over Floor Name/Room Name

4.5.1. Floor Options

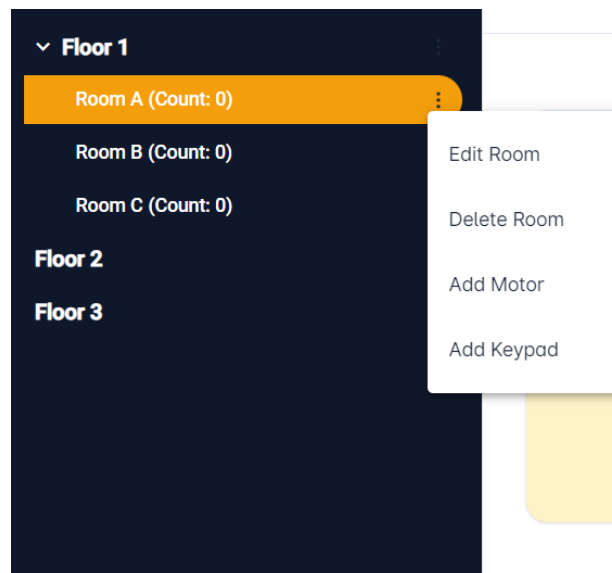
- Edit Floor: To edit Floor Name
- Delete Floor: To remove a floor from the Floor Map. All SDN devices attached to Floor, go to unassigned devices in Device Map when a Floor is deleted
- Add Room: To add Room into selected Floor

4.5.2. Room Options

- Edit Room: To edit Room Name
- Delete Room: To remove Room from Floor Map. All SDN devices attached to Room go to unassigned devices in Device Map when Room is deleted

4.5.3. SDN Device options

- Edit: To change Motor Label/ Keypad Name
- Delete: Delete device from floor plan, goes to unassigned devices in Device Map
- Double-click on device name to change the Motor Label or Keypad Name

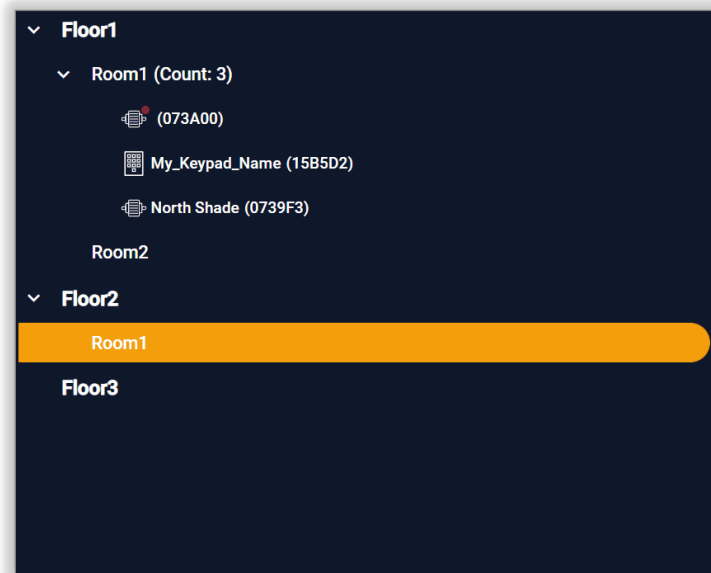


Add SDN devices to any room by drag and drop from Device Map.

Move any single SDN device between rooms by drag & drop.

Double-Click on Floor/Room/SDN Device allows to change Floor Name/Room Name/Motor Label/Keypad Name.

Drag & Drop Floor/Room to rearrange order.

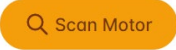



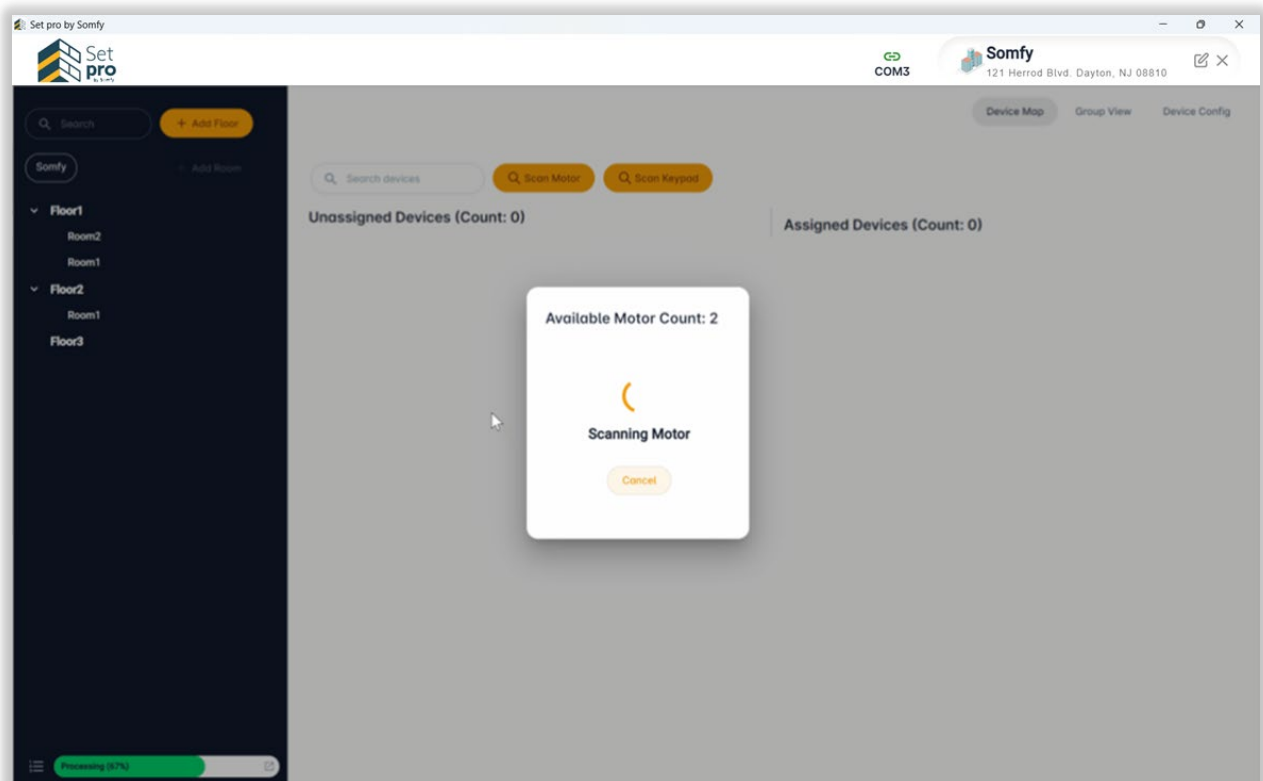
5. Device Map

Device Map lists all devices in the project. From Device Map view user can discover SDN devices,

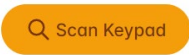
5.1. Discover SDN Devices

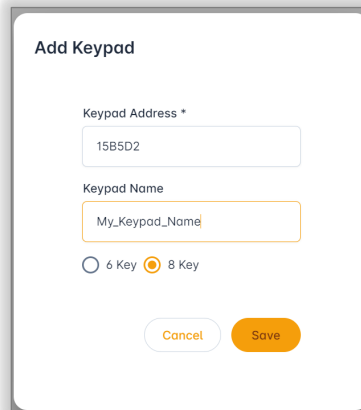
5.1.1. Discover SDN Motors

- Click on 
- Discovered Motor Counts will be displayed
- Once Node Discovery is finished, it will fetch NodeLabels of each motor
- After NodeLabel limit of each motor will be checked.
- User can Confirm or cancel to scan group. Group Scan will inquire groups of each motor and prepare list of group which will be available in Group View. Group scan can also be performed from Group View.
- Upon discovery completion all motors will be listed with NodeLabel and NodeID.
- Motors which are not assigned to any rooms will be displayed under unassigned devices.
- Separate collapsible list will be displayed for each motor type (ST30, ST50, etc.). Only NodeID will be displayed for motors without NodeLabel
- Motors without limits set will be displayed with a flashing red dot over it. 



5.1.2. Discover Keypad

- Click on 
- A prompt will be open if user wants to stop discovery
- Locate the physical keypad and press buttons 7 & 8 together(Arrow buttons)
- The Keypad will be discovered and a prompt with the KeypadID will be displayed



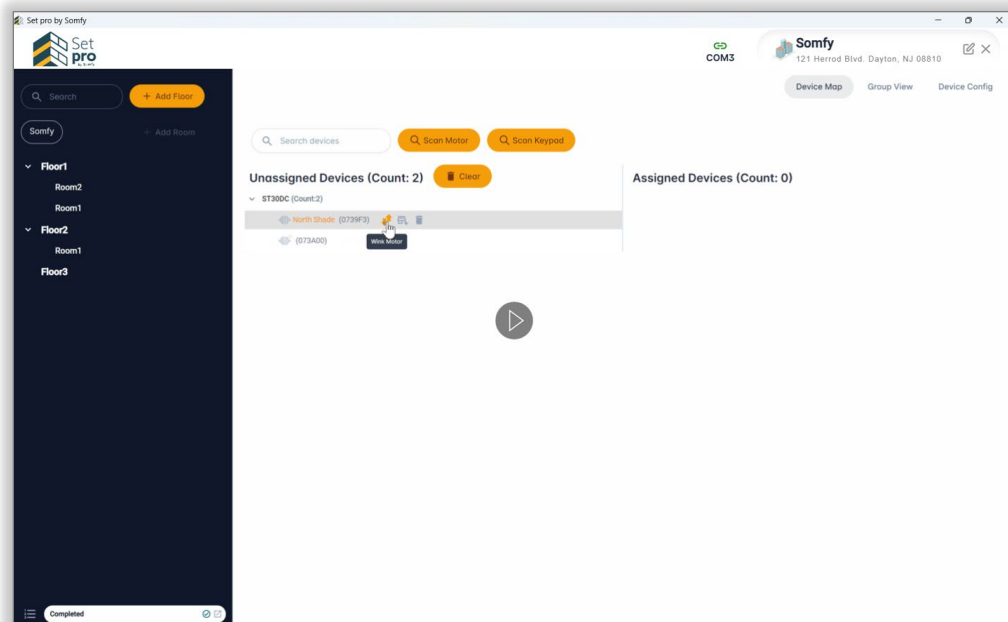
The 'Add Keypad' dialog box contains the following fields and options:

- Keypad Address ***: A text input field containing '15B5D2'.
- Keypad Name**: A text input field containing 'My_Keypad_Name'.
- Keypad Type**: Two radio buttons labeled '6 Key' and '8 Key'. The '8 Key' option is selected.
- Buttons**: 'Cancel' and 'Save' buttons at the bottom.

- Type the reference name in Keypad Name Field
- Select Keypad type(6 or 8-button) and click the Save Button
- The Keypad now appears in unassigned devices

5.2. Identify Motor

- Unassigned motors always have the wink option available when hovering over the motors
- Once clicked, the wink option will be highlighted, and the motor will wink for 5 minutes
- Stop winking by pressing highlighted wink icon again or it will automatically stop winking after 5 minutes



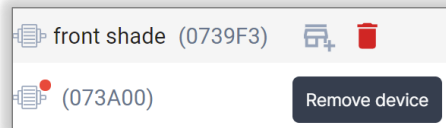
5.3. Search SDN Devices

- Search any device by NodeID or NodeLabel

5.4. Clear Unassigned Discovered Devices


- Only unassigned devices can be cleared from the list.

5.4.1. Clear Individual Device



- Click on the “Remove device” Button to remove an individual device from discovered devices

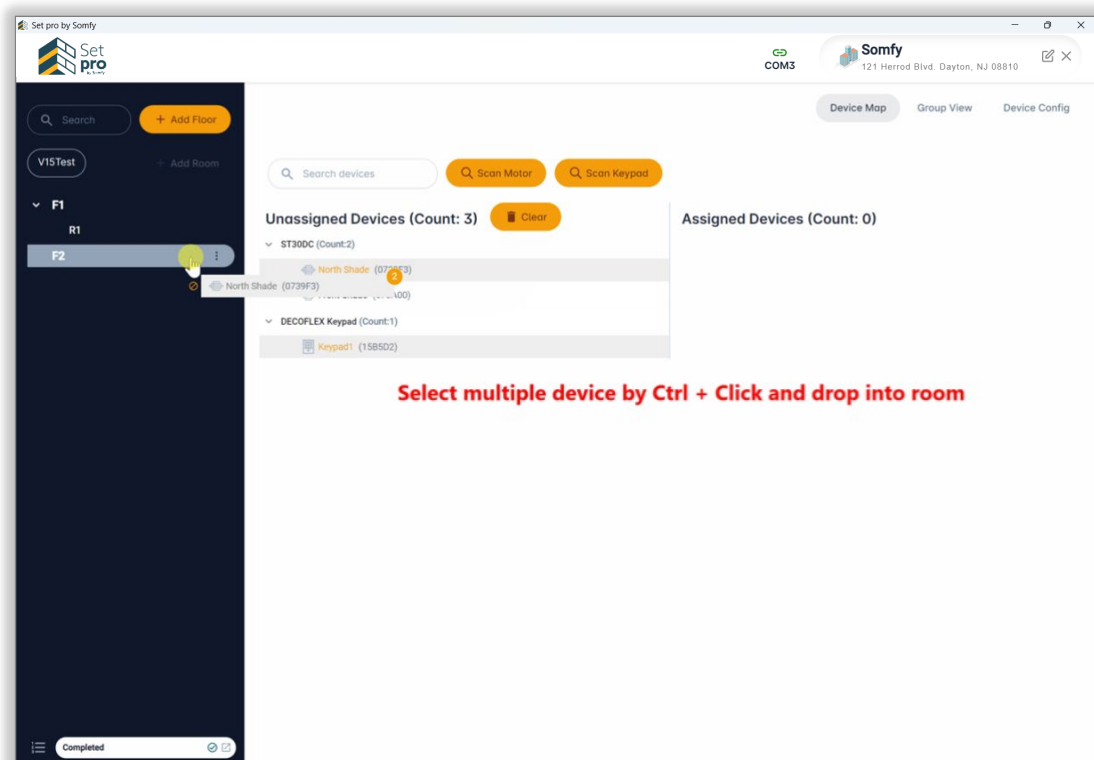
5.4.2. Clear All Unassigned Devices

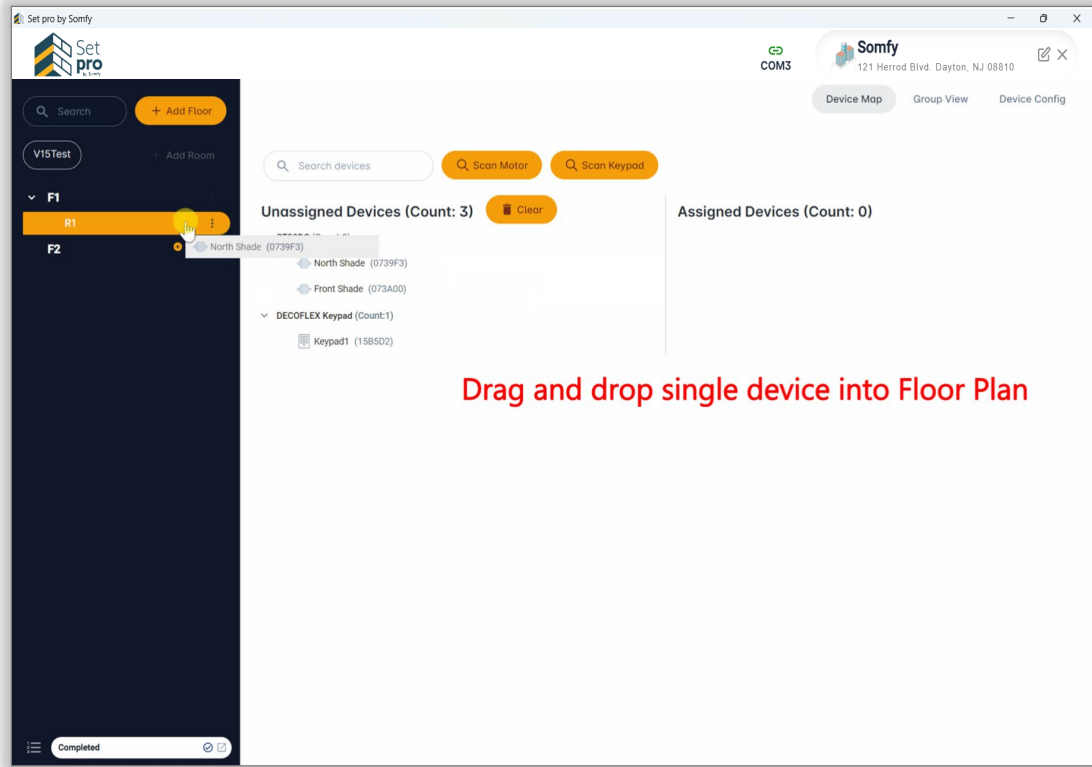
- Click on  to remove all discovered devices which are unassigned

5.5. Assign Devices in Room

Drag & Drop option:

- Select multiple devices by Ctrl + click. Use Shift + arrow keys for listed devices
- Use Ctrl + A to select all listed devices
- Drag selected devices to desired room and drop it
- Devices cannot be dropped onto floors
- Once assigned to a room, devices will appear in assigned devices list





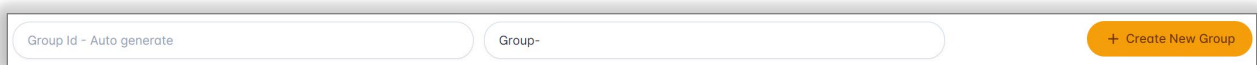
Group View

5.6. Create Group Map

- Click on **Scan Group** to create group Map of all discovered motors.
- All group will be listed along with collapsible menu list with motor in the group and count of motors in the group
- Group names are generated from GroupID. Group Name can be changed in software by double-clicking on it.

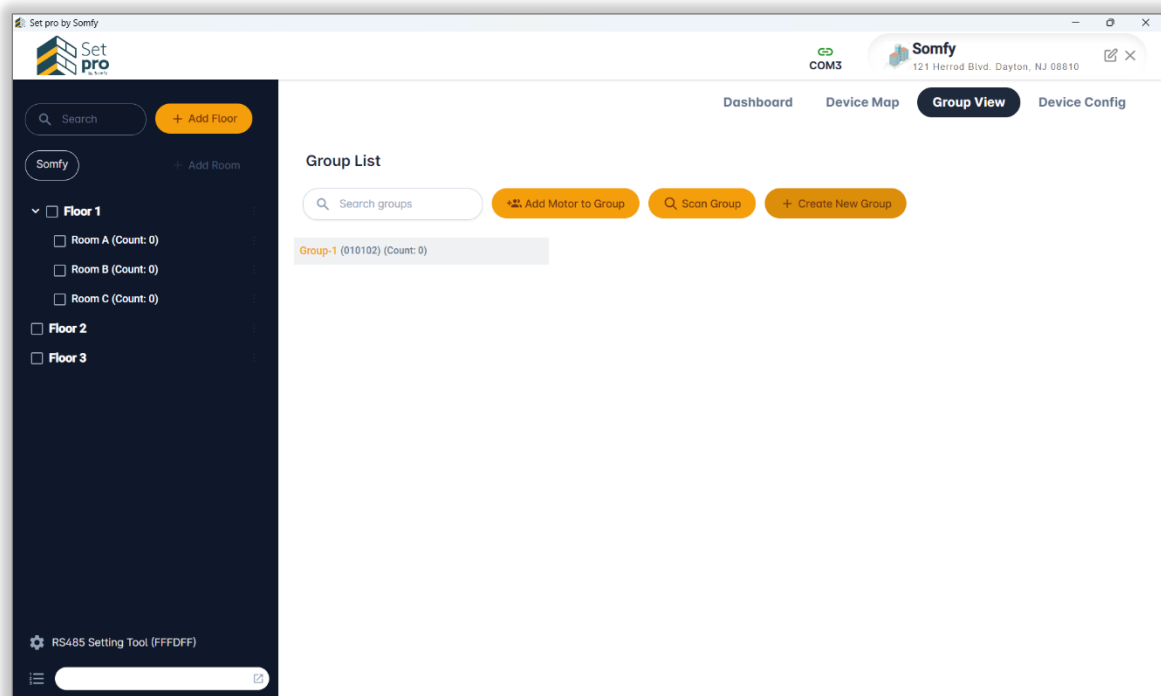
NOTE: Group name is for user reference only, Group Name is not stored in the motor

5.7. Create New Group



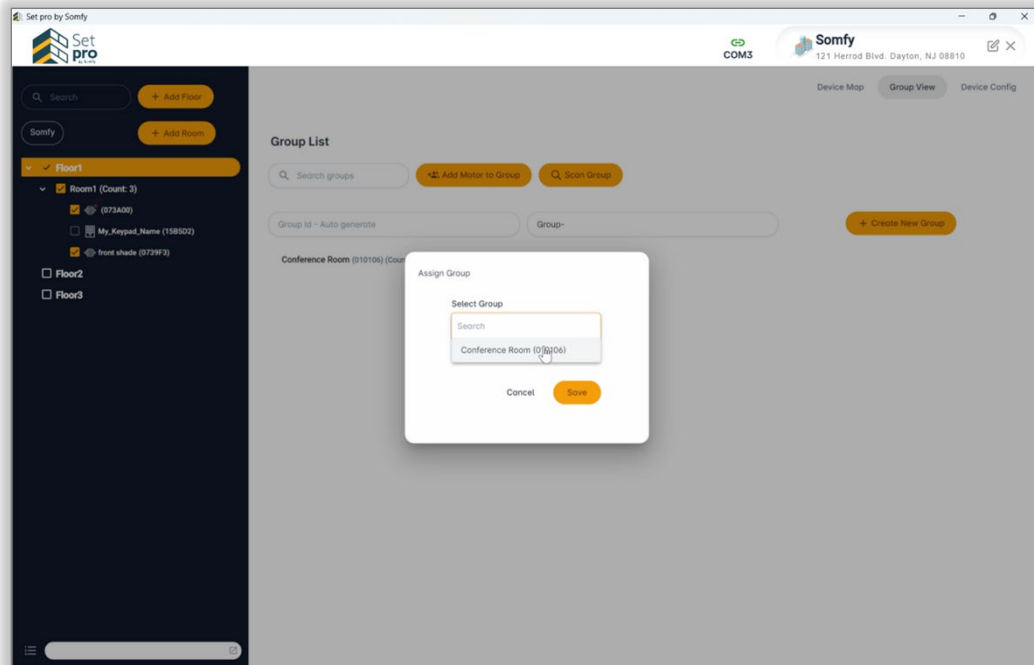
The screenshot shows two input fields. The first field is labeled "Group Id - Auto generate" and contains the text "Group-". The second field is labeled "Group-" and is empty. To the right of the second field is a yellow button with a plus sign and the text "+ Create New Group".

- Group ID is generated automatically if user do not edit GroupID field
- Edit the desired group name in Group Name field and click on "+ Create New Group" button



5.8. Assign Motors to Group

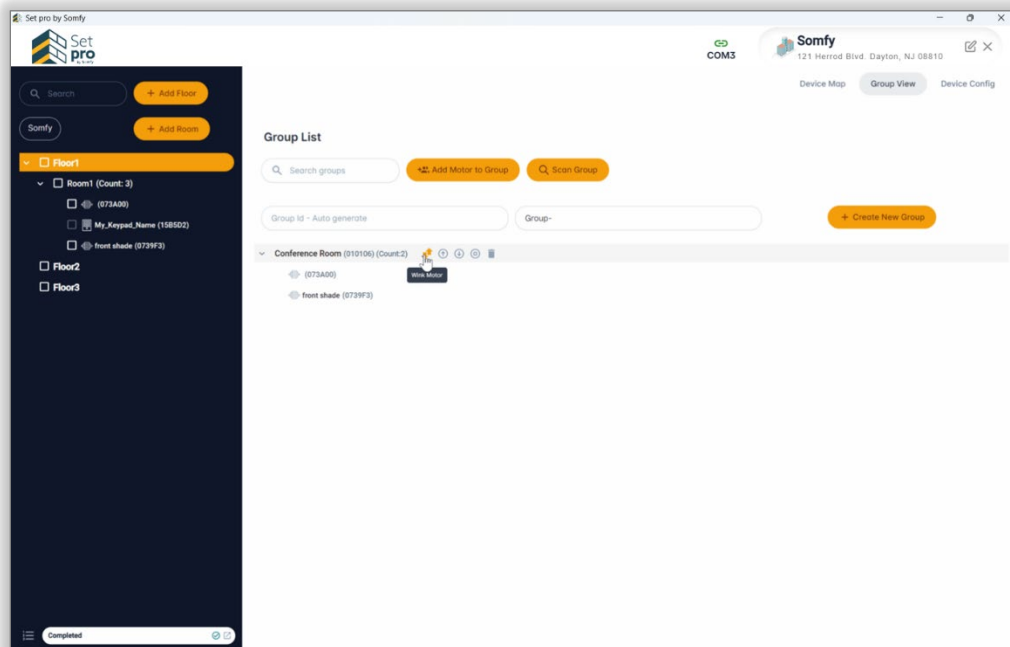
- Select motors by checking boxes besides motors. Select Floor/Room to move all motors within that Floor/Room into group.
- Click **+ Add Motor to Group**
- Select the appropriate group from drop down list from the popup window
- Click "Save"



5.9. Group Operations

Following operations can be done group of motors

- Wink all motors in the group
- Up/Down/Stop all motors in the group
- Delete individual motors from the group
- Delete Group



6. Device Config

6.1. Open Device Config Tab

Select the appropriate device from the Floor Plan View.

Device config menu for selected device will appear in tabbed view.

6.2. Motor Config Options

6.2.1. Control Tab

Simple Motor Movements

The screenshot displays the control interface for a motor named 'North Shade (ST30DC)'. At the top, it shows the current position as 636 (59%). Below this, there are several numbered callouts: 5 points to the current position, 6 to a refresh icon, and 7 to a stop icon. A tabbed menu is visible with 'Control' selected and highlighted by a red box. The main area contains four distinct motor movement controls, each with a numbered callout: 1. 'Step Movement' with up/down arrows and a '10 ms*10' input field. 2. 'UP/DOWN movement by pulse' with up/down arrows and a '10 Pulse' input field. 3. 'Absolute Position Movement' with 'Enter Position' text, two input fields (one with '0 %' and one with '0 Pulse'), and a 'GO' button. 4. 'Move to End' with up/down arrows and a 'Stop' button.

1. UP/DOWN Movement by milli second*10 input from textbox
2. UP/DOWN movement by pulse
3. Move motor to specific position by pulse count/percentage
4. UP Limit/Down Limit/Stop movement
5. Current position of Motor
6. Update Motor position data
7. Wink motor

6.2.2. Intermediate Positions (IPs)

View Intermediate Position, Click on IP to go to Intermediate Position, Erase All IPs, Autogenerate IP (1-16), Set IP @current, Set IP @fixed position/pulse, Erase individual IP

The screenshot shows the 'Intermediate Positions' control interface for a North Shade (ST30DC) motor. The interface is divided into several sections:

- Navigation:** A menu at the top includes 'Control', 'Intermediate Positions' (highlighted with a red box), 'Group', 'Settings', 'Actions', and 'Diag.'.
- Go to IP:** A section with up and down arrows (labeled '2') for navigating between IP positions.
- Intermediate Positions List:** A grid of 16 positions (1-16) with their respective percentages. Position 1 (63%) is highlighted in orange, indicating it is the current position. A green dashed box labeled '1' encloses the entire list.
- Control Buttons:** Three buttons at the top right: 'Auto Generate IPs' (labeled '3'), 'Erase All IPs' (labeled '4'), and 'Refresh' (labeled '5').
- Adjust Current Position:** A section labeled 'Adjust Current Position' with up and down arrows and a 'ms*10' input field (labeled '6').
- Enter Value For IP1:** A section with two input fields (one for percentage, one for pulse) and 'GO' and 'SET' buttons (labeled '7' and '8').
- Action Buttons:** Three buttons at the bottom right: 'Go To IP1' (labeled '9'), 'Set IP1 at Current' (labeled '10'), and 'Erase IP1' (labeled '11').

1. List of Intermediate positions: Click to go to Intermediate Position. Click to select IP.
NOTE: Selected IP is shown using an Orange button
2. Go to Next IP UP/Next IP DOWN
3. Auto Generate Intermediate Position (select from 1-16)
4. Erase all Intermediate Position settings
5. Refresh Intermediate Position
6. Adjustment to current position by pulse/ms (millisecond)
7. Go to Pulse/% location
8. Set selected Intermediate Position at input pulse/%
9. Go to selected Intermediate Position
10. Set selected Intermediate Position at current motor position
11. Erase selected Intermediate Position

6.2.3. Motor Group

List Groups with Group Name, delete group, delete all groups, add motor to a group

North Shade (ST30DC)
Current Pos.: 33(3%)

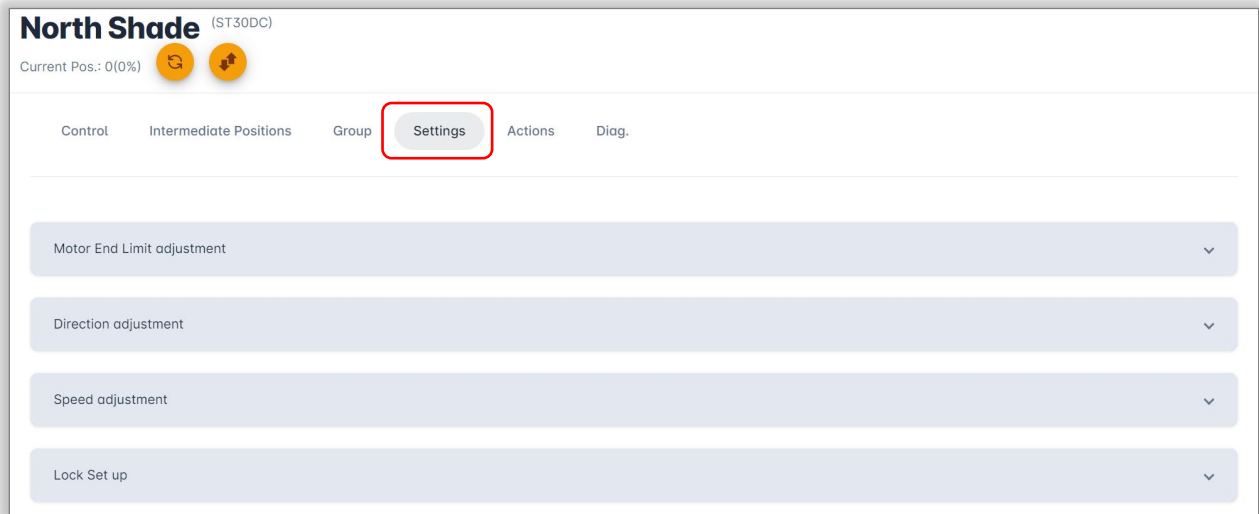
Control Intermediate Positions **Group** Settings Actions Diag.

3 Add to Existing Group 4 Remove from All Groups

0: Group-010107	010107	5
1: Group-01010B	01010B	
2: Group-010101	010101	
3: Group-212121	212121	
4: Group-000002	000002	
5: Group-000001	000001	
6: Group-010104	010104	
7: Group-010110	010110	

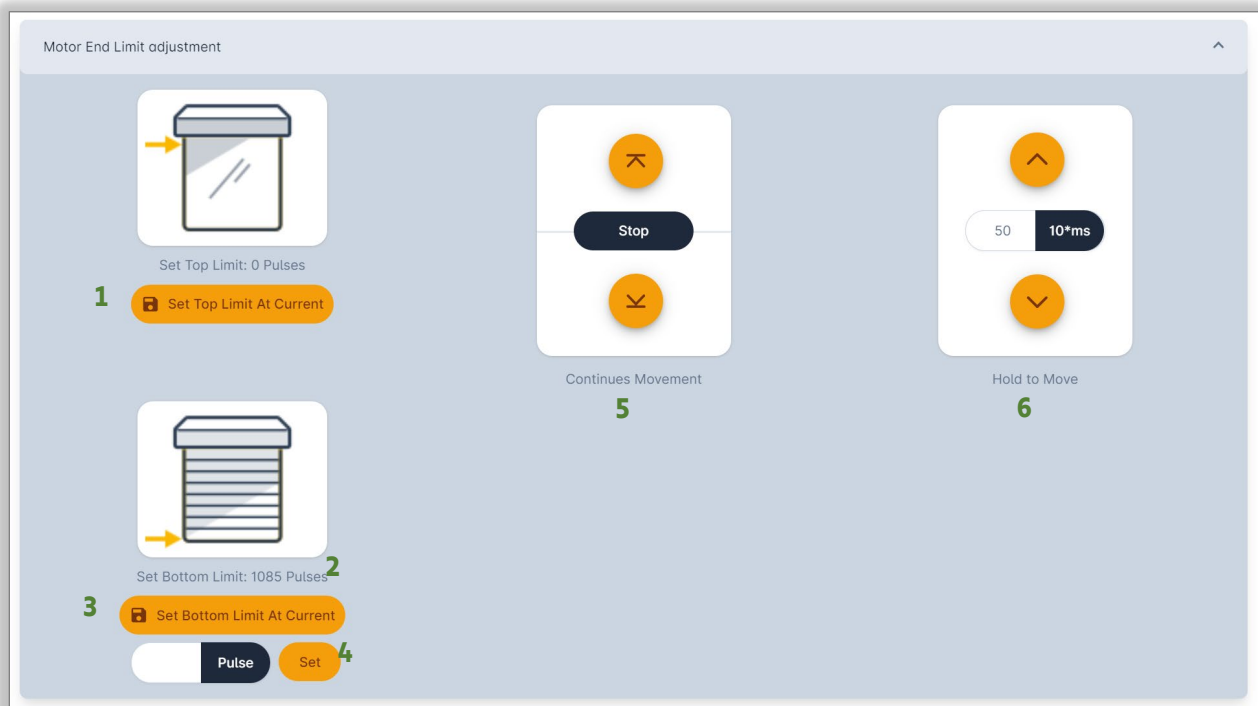
1. List of current motor Groups
2. Update list of Groups
3. Add motor to existing group (Group list is available in Group View tab).
NOTE: New group cannot be created here.
4. Remove motor from all groups
5. Remove individual group

6.2.4. Motor Settings



1. Expand/Collapse the desired setting option

6.2.4.1. Motor End Limit adjustment

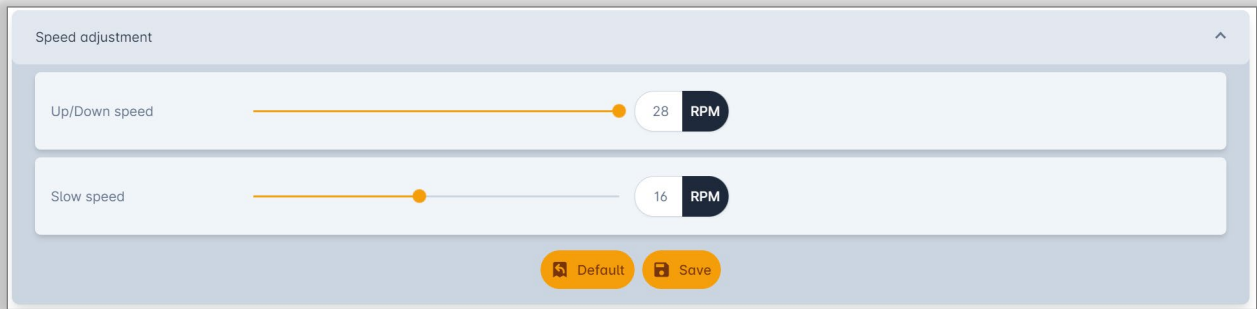


1. Set Top limit @current motor position
2. Pulse count of current end limit
3. Set Bottom limit @current motor position
4. Set Bottom limit @pulse count provided in text box
5. Go to UP/DOWN limit
6. Move motor beyond limits. Hold UP/DOWN to move, release to stop movement.

6.2.4.2. Direction adjustment

1. Click on direction to change motor direction
NOTE: Current direction is not able to be selected

6.2.4.3. Speed adjustment



1. Click on "Default" to set default speed
2. Change Up/Down speed setting or Slow speed settings and click "Save" to set the adjustment

6.2.4.4. Lock Set up



1. Click to Lock/Unlock Network
2. Click to Lock/Unlock Position
3. Set Lock/Unlock priority between Network or Position
4. Refresh Lock status
5. Click to go to Intermediate Position
6. Go to specific position (% or Pulse count)
7. Go to UP Limit, DOWN Limit, or STOP movement

6.2.5. Action

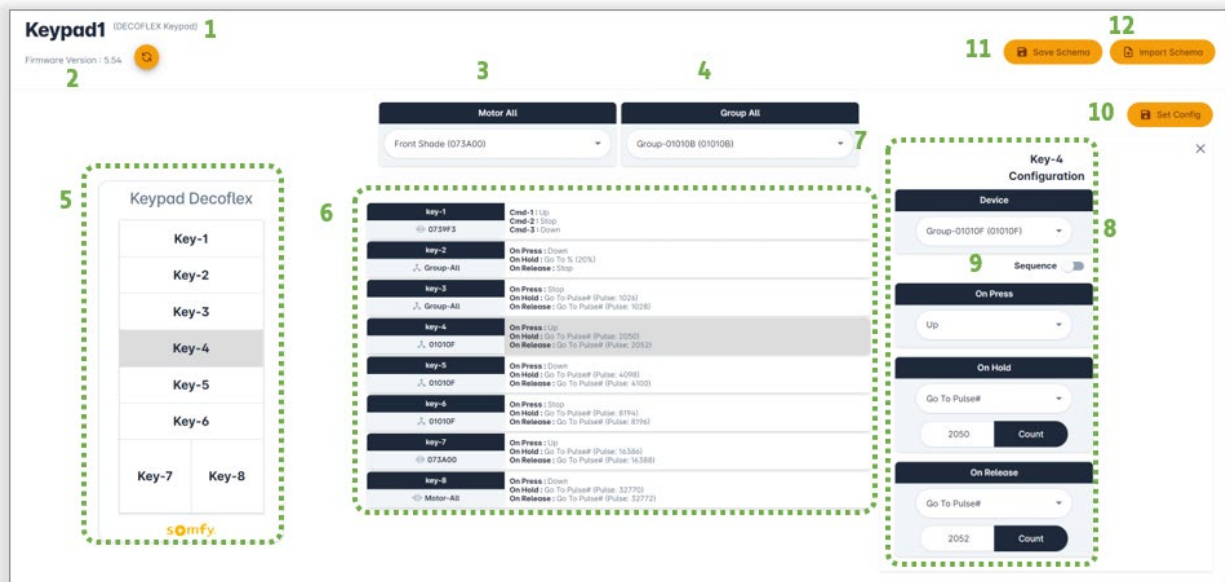
Click to check motor firmware version, Wink to get visual feedback or reset motor to factory default motor settings.

6.2.6. Diag

Click to retrieve diagnostic information from motor

6.3. Keypad Configuration

Open Device Config Tab, then select desired keypad from Floor Plan View. Keypad Configuration options will appear in the Tabbed View.

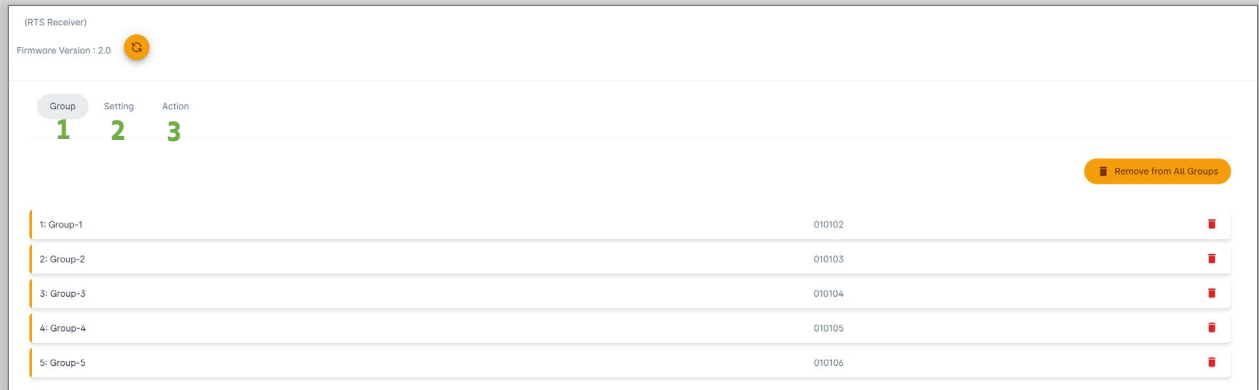


1. Keypad Name (Not stored in keypad, for project reference only)
2. Keypad Firmware Version
3. Motor All option device selection
4. Group All option group selection
5. Keypad View: Press on keypad button to open key configuration options
6. Key settings for the selected Key
7. Selected Key Configuration options
8. Device selection for selected key
9. Sequence option
10. Set Configuration: Programs keypad
11. Save Schema of keypad
12. Import Schema of keypad

NOTE: Group_All functionality will only work with Keypad firmware version 5.54 or later. Old SDN Keypad Tool will not program Group_All functionality in keypads with firmware 5.54 or later.

6.4. RTS Receiver Configuration

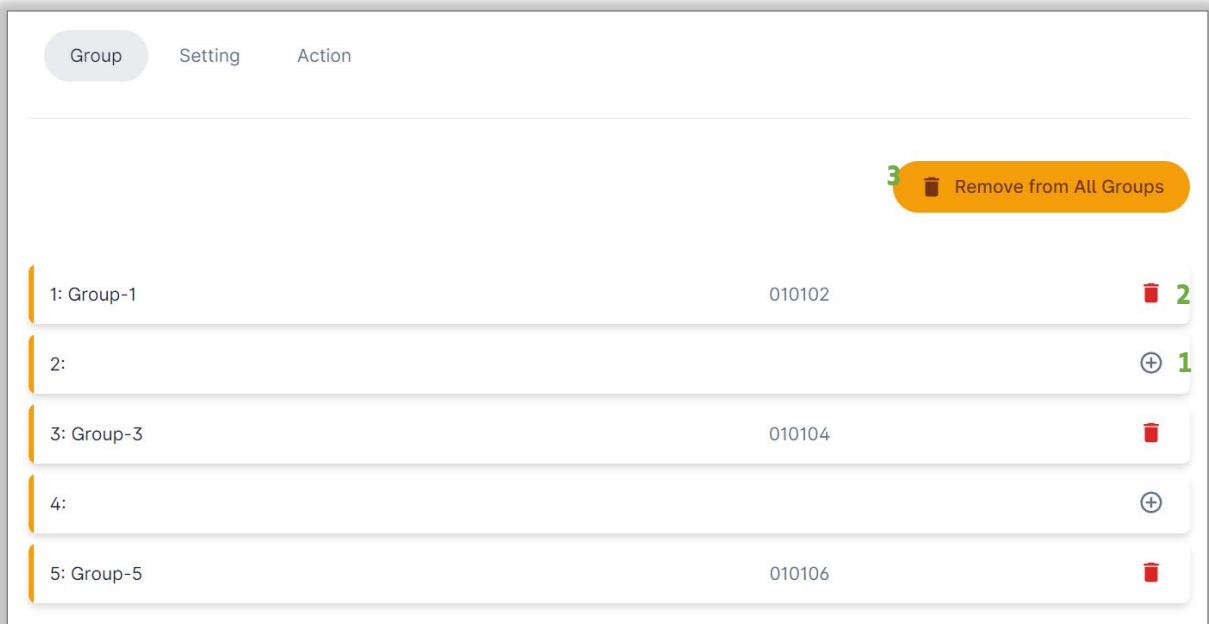
Device Config Tab, then select desired RTS Receiver from Floor Plan View. RTS Receiver options will appear in the Tabbed View.



There are three tabs to the RTS Receiver Configuration menu:

1. Group: Set/Delete RTS Receiver Groups (Group must be created in Group View to add into RTS Receiver)
2. Setting: Program/Delete RTS Channels using this menu
3. Action: Factory Default Setting/ Firmware information

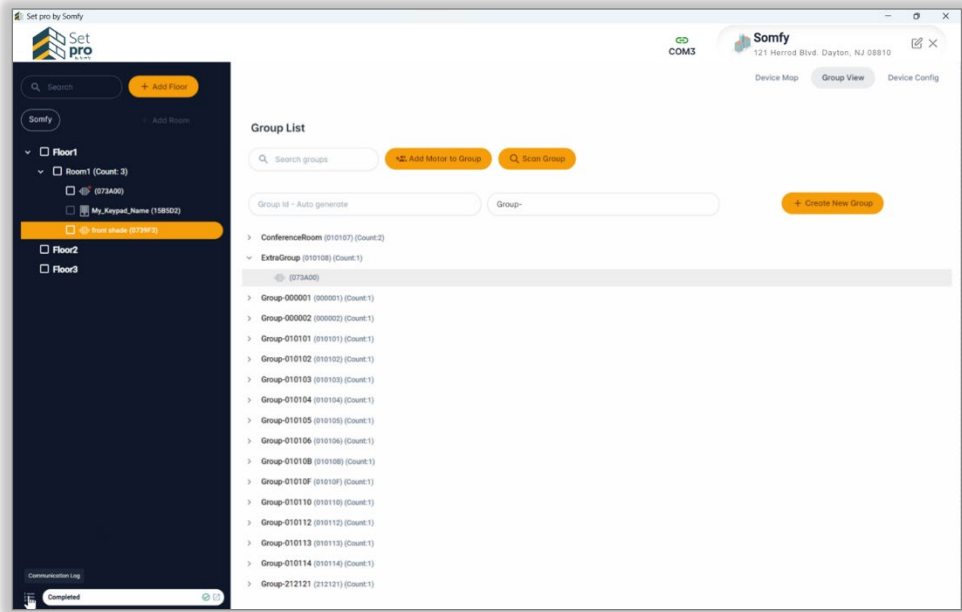
6.4.1 Group Operations



1. Click the [Add icon] icon to add group on specific position
2. Click the [Red trash icon] icon to delete group on specific position
3. Remove all groups from RTS Receiver

7. Communication Log

7.1. Open Communication Log



7.2. Communication Log features

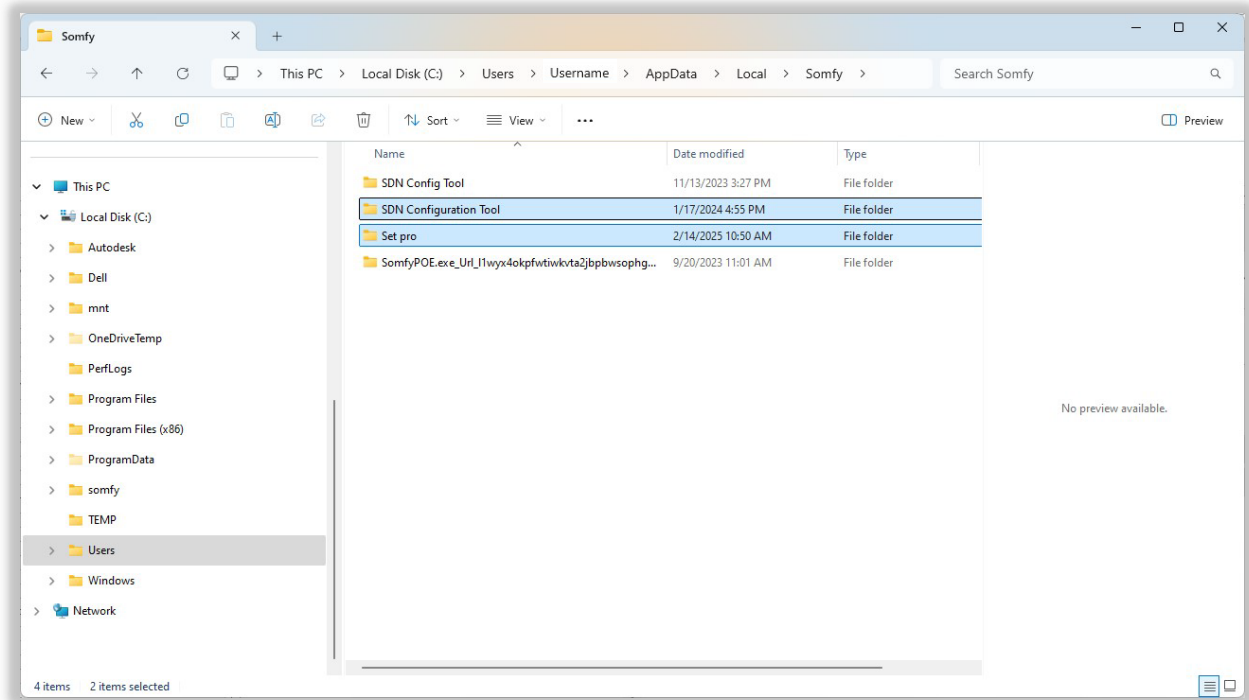
- Copy SDN string
- Send SDN string from Communication Log
- Filter TX/RX Messages
- Download Log in Excel format
- Clear Communication Log

No.	Time	Source Node type	Dest Node type	Source	Dest	Command	Data	Action
7	01/06/22 13:29:18.454	Master-RS485	All Devices	010106	000000	CTRL_MOVE10	00000000	[Copy] [Send]
8	01/06/22 13:29:22.767	Master-RS485	All Devices	010106	000000	CTRL_STOP	01	[Copy] [Send]
9	01/06/22 13:29:30.680	Master-RS485	ST30DC	010000	073A00	SET_GROUP_ADDR	00000000	[Copy] [Send]
10	01/06/22 13:29:30.793	ST30DC	Master-RS485	073A00	010000	ACK		[Copy] [Send]
11	01/06/22 13:29:36.362	Master-RS485	ST30DC	010000	0739F3	SET_GROUP_ADDR	00000000	[Copy] [Send]
12	01/06/22 13:29:36.710	ST30DC	Master-RS485	0739F3	010000	ACK		[Copy] [Send]
13	01/06/22 13:40:22.019	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_POSITION		[Copy] [Send]
14	01/06/22 13:40:22.289	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_POSITION	820238FFFF	[Copy] [Send]
15	01/06/22 13:40:22.443	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_LIMITS		[Copy] [Send]
16	01/06/22 13:40:22.537	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_LIMITS	00003D04	[Copy] [Send]
17	01/06/22 13:40:42.608	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	00	[Copy] [Send]
18	01/06/22 13:40:42.735	ST30DC	Master-RS485	0739F3	010000	nACK	01	[Copy] [Send]
19	01/06/22 13:40:42.842	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	01	[Copy] [Send]
20	01/06/22 13:40:42.943	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_IP	01FFFFFF	[Copy] [Send]
21	01/06/22 13:40:43.068	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	02	[Copy] [Send]
22	01/06/22 13:40:43.166	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_IP	0244011E	[Copy] [Send]
23	01/06/22 13:40:43.292	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	03	[Copy] [Send]
24	01/06/22 13:40:43.384	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_IP	03FFFFFF	[Copy] [Send]
25	01/06/22 13:40:43.505	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	04	[Copy] [Send]
26	01/06/22 13:40:43.586	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_IP	04FFFFFF	[Copy] [Send]
27	01/06/22 13:40:43.704	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	05	[Copy] [Send]
28	01/06/22 13:40:43.801	ST30DC	Master-RS485	0739F3	010000	POST_MOTOR_IP	05FFFFFF	[Copy] [Send]
29	01/06/22 13:40:43.921	Master-RS485	ST30DC	010000	0739F3	GET_MOTOR_IP	06	[Copy] [Send]

APPENDIX

[APPENDIX A] IMPORT PROJECTS TO NEW SOFTWARE

- 1) CONFIRM Set pro V2.0.8 is installed properly
 - a. NOTE: Projects created with Set pro will not be visible after this process so do not create new projects before transferring projects from old software
- 2) BROWSE to C:\Users\- 3) NAVIGATE to the Local Disk (C:) Users\- 4) COPY all files in the folder
- 5) PASTE all the files into C:\Users\- 6) LAUNCH Set pro by Somfy V2.0.8 and then all their project files will be visible



FOR QUESTIONS OR ASSISTANCE PLEASE CONTACT TECHNICAL SUPPORT:

(800) 22-SOMFY (76639)

Get answers to your questions from our Somfy FAQ page: www.somfysystems.com/en-us/support/faq

Follow the steps to access Service & Support.



About Somfy®

For over 50 years, Somfy has been pioneering innovative motorization and automated solutions for window coverings and exterior shading products. With comfort, ease of use, security and sustainability in mind, our seamless and connected solutions are designed to help people make the move to living spaces impactful for humans and with a reduced impact on nature.

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